

# ROBOTICS WORKSHOP CONTENT



## *Workshop Highlights*

- Construct robot by scratch.
- Concept of development board
- Move Robot in Different Direction.
- Learn wiring of Motor Driver.
- Concept of Motor Driver.
- Connection of Microcontroller to Motor

## *Topics to be covered in workshop*

### *The Microcontroller Platform*

- The Open-Microcontroller Platform
- Development board Basics.
- Microcontroller Board Layout & Architecture.
- Testing the development board.
- Setting IDE
- Interfacing of board (Hardware with Software)

### *Programming fundamentals (C language)*

- Arduino Programming
- Programming basics
- Uses of keywords
- Writing the first code.

### *Introduction to Robotics*

- Types of Robots.
- Demand of Robots.
- Uses of Robots.
- Future of Robots.

### *Construction & Wiring of Robots*

- Identifying parts required for building a Robot.

- *Construction of Robot.*
- *Introduction to Motor Driver.*
- *Motor Driver Working.*
- *Wiring between Microcontroller & Motor Driver*

### **Projects:**

- *Project 1:* *Moving robot forward*
- *Project 2:* *Moving robot backward*
- *Project 3:* *Making a square*
- *Project 4:* *Angular right*
- *Project 5:* *Angular left*
- *Project 6:* *Axial turn*
- *Project 7:* *Radial turn*
- *Project 8:* *Permanent Stop*

### **KIT Content of Sensor Robot**

- *Arduino Circuit Board*
- *Micro Controller-ATMEL Atmega 328*
- *Operating Voltage -5V*
- *Input Voltage – 6V-20V*
- *Digital I/O Pins - 14 out of which 6 provide PWM*
- *Analog Pins – 8*
- *DC Current per I/O pin -40mA*
- *Flash Memory – 16KB*
- *SRAM – 1KB*
- *EEPROM - 512Bytes*
- *Clock Speed – 16MHz*
- *USB-UART Converter*
- *Proper Indicators LED's*
- *USB/EXT Input Voltage*
- *5V output supply pins – 3*
- *3.3V output supple pins – 1*

- Breadboard Compatibility(Dimension of a 40 pin DIP IC)
- 2 Multipurpose Photo Sensor
- 1 Sound Sensor
- ACRYLIC Multipurpose Robot Chasis
- Plastic Wheels
- DC Motors
- 360' Castor Wheel
- Battery(9V)
- A to B USB Cable for Programing
- Connecting Wires
- Screw

### *Course Outcome*

*After completion of the course students will be able to design their own bots.They will learn about the components functioning and their application in order to develop their own projects.*

### *Requirements from college:*

- Faculty & 2 Student Co-coordinator's Name & Number
- Projector/screen for presentation purpose.
- Public address system or two mikes (cordless if possible).
- Seminar Hall with capacity proportional to the Student count
- A computer/Laptop in team of 5.
- One Extension Board in a group of 5

# 8 Advantages of Robotics



Fewer errors

Higher quality

Less downtime

Higher productivity

Less space utilization

More energy efficiency

Improved security and control

Reduction in pick, pack and ship times

